Developing a future-ready biosecurity system



Innovation, Legislation and Education

Biosecurity Strategy and Reform Division

Department of Agriculture, Fisheries and Forestry

About us

Innovation Pilots

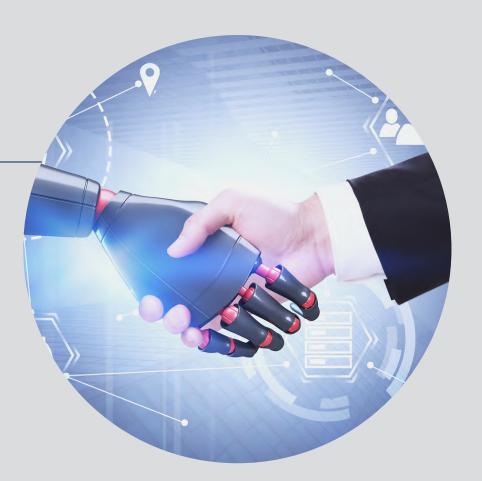
Test innovative technologies that are <u>available now</u> to optimise <u>how we work today</u>

Pilots are run in short, sharp cycles to test ideas in the field which involves pilot design, sourcing assets and supporting pilot activities right through to evaluation & final recommendations.

Biosecurity Innovation Program

Invests in new technologies and approaches to enhance Australia's biosecurity system – with applications open to the public.

It supports collaboration between industry and government and helps Australia maintain our favourable pest and disease status and our access to export markets.







Some of our Innovation Pilots ...



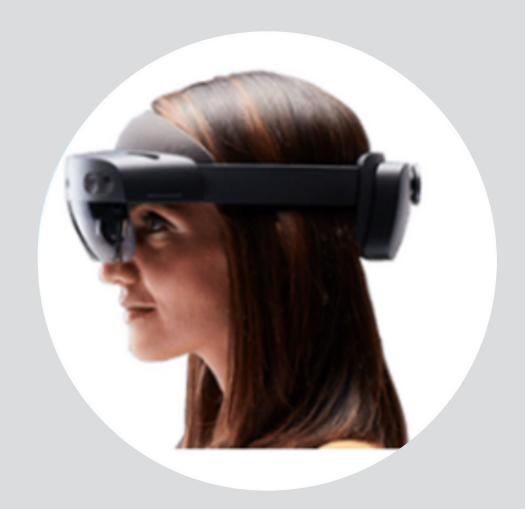
'temi' the telepresence robot

Discovering new ways of doing things without the need to be physically present



Remotely Operated Vehicles

Testing the effectiveness of ROV's to conduct biofouling inspections



Livestreaming

Further testing our livestreaming capability with new technology



Some of our BIP projects



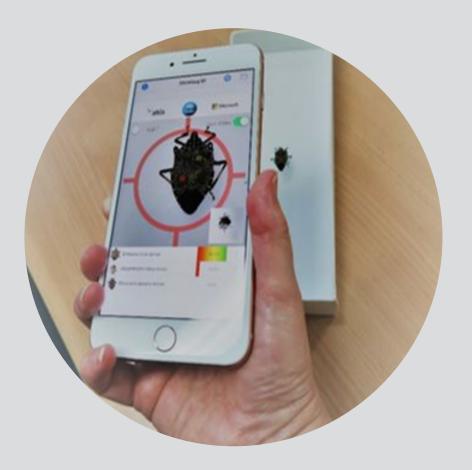
Cloud repository for Al training data

Scope and design a solution for a cloud-based Al training repository



eDNA for biosecurity identification

Testing eDNA technology to detect pests, parasites and diseases



Brown Marmorated Stink Bug App

Mobile identification of brown marmorated stink bug



Boston Dynamic's 'Spot'

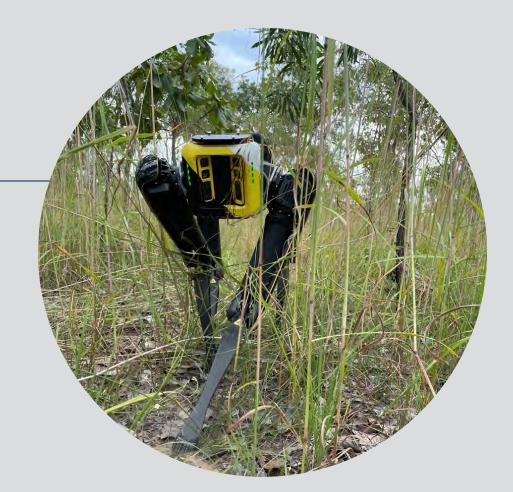
Boston Dynamic's 'Spot' is a four-footed agile robot that can traverse rough terrain with ease and undertake routine inspections remotely.

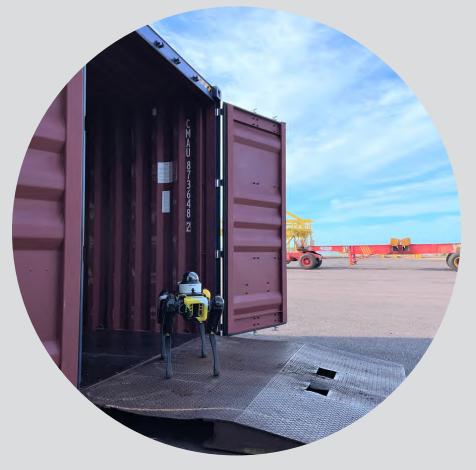
Spot can carry a number of payloads (up to 14kg) that can include imagery and sensor devices and an arm that can open doors and pick up items.

Spot can live-stream, take images, collect data, detect harmful gases, round up sheep and even dance!

We will be:

- testing Spot in container and vehicle inspections
- exploring integration with other technologies
- building on the robot's autonomous capability



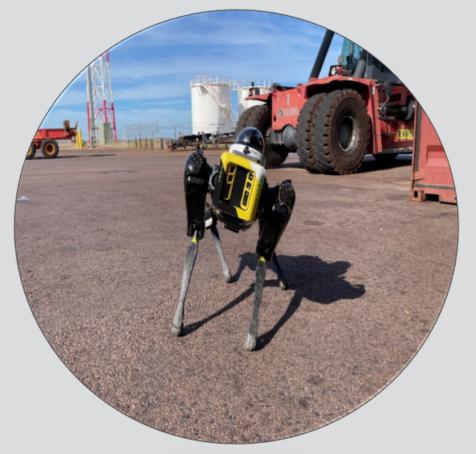




Spot specifications

- **Length** = 1100 cm
- Width = 500 cm
- Default Height (Walking) = 610 cm
- **Max speed** = 1.6 m/s
- Net mass/weight = 32.7 kg
- Average runtime (no payload) = 90 mins
- Standby time = 180 mins
- Recharge time = 120 mins
- PAYLOADS Max weight = 14 kg







Contact us if you want to talk more about what we do and for further information.

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